Agent Mobility in 2D Landscapes (Bonus: Some UI Customization)

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Agent Mobility

- Thus far, we have looked at spatial dynamics where each agent remains stationary
 - Continuous space (static & dynamic populations)
 - Discrete space (cellular automata)

2D Spatial Embedding: Mobility Implications

- Continuous embedding (e.g. Wandering elephants)
 - No physical exclusion: Agents are assumed to be small compared to landscape scale, and exhibit arbitrary spatial density without interfering
 - Agents move
 - In a direction
 - With some speed
- Discrete cells (e.g. Agent-based predator prey, Schelling Segregation)
 - Divided into "Columns" and "Rows"
 - Physical exclusion: Only one agent in a cell at a time
 - Agents move continuously or discontinuously from cell to cell



Hands on Model Use Ahead



Load model: Wandering Elephants.alp

Environment



Landscape Information



Agent Movement: Periodic Movement Changes

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New Direction Change Function Info



New Direction Change: Function "Body"



(Main) Defining a Custom Angle Distribution

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DistrAngle - Variable

Data for Custom Distribution

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Looking at body of this function (method) Heading Towards Resource



Selection

Handling Agent Arrival at Destination (Not Currently Used in this Model)



Handling Arrival Events in Statecharts



Resumption of Wandering After Slaking Thirst

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Handling of Movement Logic



Rerouting Around Barriers (Boundaries & Water) Poor Style – entire logic, conditions (checks on boundaries, whether water) & rerouting

Logic should all be in separate functions from this & from each other). Remove constants



Environment: Updating Vegetation

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Intern	<pre>if (vegetation[1][j] > 0) vegetation[i][i] = limitMax(vegetation[i][i] + 15, (40 - altitude[i][i]) * 1</pre>	Final State
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Continuous Space: Relevant Methods (To call on *Agent*)

- Already covered
 - moveTo(x,y) : initiates agent movement to location
 - setVelocity(v)
- Basic info
 - getX()/getY()
 - setXY(x,y): initial location
 - jumpTo(x,y): moves agent to location
 - isMoving()
 - getTargetX()/getTargetY()
 - Where heading to?
 - setRotation()/ getRotation()

Environment Happens to Handle Process of Maintaining Environmental Dynamics



environment - Environment



Hands on Model Use Ahead



Load model: Schelling Segregation.alp

A Model to Examine the Emergence of Segregation



A Discrete Spatial Environment with Random Agent Positioning



Selection

Population Dependence on the Population



Slider Input Sets Parameter Value

slider - Slider

Person is Assigned a Randomly Picked Color

Core Segregation (Movement) Logic

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Sharing same colour		Agent[] neighbors = getNeighbors();	· · · · · · · ·	
(chould be in diff		<pre>satisfied = true: //no neighbors is good too</pre>	surrounding individuals	
		return;		
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runctionj.		for(Agent a : neighbors)	thrachold	
		<pre>if(((Person)a).color.equals(color)) nsame++:</pre>	threshold	Analysis
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		if(! satisfied && randomTrue(0.3))		Se More Libraries
		jumpToRandomEmptyCell();	<u>30% chance of moving</u>	

Experiment: Simulation Sets Parameter Assumptions

Simulation - SimulationExperiment

Add a Parameter to Main

Experiment: Add a Slider!

Setting the Slider Properties

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🗖 🗖 🐻 Main - -- -🎦 Project 🖾 🛷 Search 🔹 Palette 🖾 🔊 Person 📓 Simulation 🖾 Person ٠ * (Micromotives and Macrobehavior, W. W. Norton and Co., 1978, pp. 147-🎭 Model 155). It represents one of the first onstructive models of a dynamical system 🍘 Parameters capable of self-organization. 🧭 Parameter Color: random... Flow Aux Variable 哘 Plain Variables Schelling placed pennies and dimes on a chess board and moved them 💟 satisfied around according to various rules. He interpreted the board as a city, with Stock Variable each square of the board representing a house or a lot. He interpreted the 🐏 Presentation Ļ Event pennies and dimes as agents representing any two groups in society, such 🔯 Simulation: Main 🍪 🛛 Dynamic Event as two different races of people, boys and girls, smokers and non-smokers, 🐏 Presentation etc. The neighborhood of an agent occupying any location on the board 🕐 🛛 Plain Variable frame consisted of the squares adjacent to this location. Thus, interior agents had Collection Variable rect1 eight neighbors while boundary agentshad either three or five neighbors. Rules could be specified that determined whether a particular agent was rect Function happy in its current location. If it was unhappy, it would try to move to Aa text: Schell... 🕞 Table Function another location on the board, or possibly just exit the board entirely. Aa text1: The Sc ... Port 🔯 image As can be expected, Schelling found that the board quickly evolved into a 🔁 Connector strongly segregated location pattern if the agents' *happiness rules* were Aa text2: AnvLog... 👍 Entry Point specified so that segregation was heavily favored. Surprisingly, however, 📧 button he also found that initially integrated boards tipped into full segregation 👝 State 💬 sliderMovementChance even if the agents' happiness rules expressed only a mild preference for Transition having neighbors of their own type. 🔦 🛛 Initial State Pointer Branch 💦 Problems 🖾 Run the model and switch to Main view (H) History State Description Location Final State • 🚺 Environment 🔲 Properties 🗙 📮 Console 🐏 sliderMovementChance - Slider General Show Name 🔲 Ignore 🗹 Public 🔲 Icon Name: sliderMovementChance Advanced Orientation: O Horizontal O Vertical Dynamic 🔼 Action Description Ο. Minimum Value: 👔 🔓 Analysis Maximum Value: 1 🐏 Presentation Default Value: 0.3 🎭 Connectivity Enabled: true 🐨 Enterprise Library Action: 🥪 More Libraries....

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Setting Value for Parameter from Slider

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Modify Person's Behavior to Depend on New Parameter

Movement in Discrete Space

- jumpToCell(int row, int column)
 - Jumps to a particular unoccupied cell
 - Precondition: destination cell is unoccupied
- moveToNextCell(int direction)
 - Moves agent into a neighbouring cell in a given direction
 - Directions: NORTH, SOUTH, EAST, WEST, NORTHEAST, NORTHWEST, SOUTHEST, SOUTHWEST
 - Precondition: destination cell is unoccupied
- jumpToRandomEmptyCell()
 - Jumps to randomly selected empty cell (returning true), returns false if no empty cell can be located

Discovery in Discrete Space

- int []findRandomEmptyCell
 - Returns row & column of an unoccupied cell
- Getting agents in cell or direction
 - getAgentAtCell(int row, int column)
 - getAgentNextToMe(int direction)
 - getNeighbors()

Important Distinction

- Suppose an agent is moving in discrete 2D space and need to be concerned about moving into the same cell as another agent
- We can readily prevent this agent from moving into another cell currently occupied
- But can we prevent this agent from colliding with another agent that wishes to move into the same cell?
 - To answer this, we need to be clear about the model of time used by agents

Synchronization & Discrete Agent Movement

- In Synchronous mode, it is difficult to know if two agents will collide using data on the current timestep
 - Even if we know where the other object was during the current timestep, it's possible it will move into the cell we wish to occupy in the next timestep
- It is simpler to handle this asynchronously
 - Here, we can have each agent update at slightly different times, and observe the location of the other agents at the current time – without any significant chance that they will move to the same place at the same time.
- Issue only arises for discrete agent movement, as this is the only case where cells are limited to contain 1 agent

Irregular Spatial Embedding

Realizing Irregular Spatial Embedding in AnyLogic

- Basic idea: people moving around follow networks of *paths*
- Irregular spatial embedding is supported directly by "Network Based Modeling" (Discrete Event Simulation)
 - This approach is individual-based, but treats agents either as flowing through and being operated on by a process or as (often interchangeable) process resources
 - We will have a brief introduction to this approach later in the week, showing how it can be combined with ABM
- With a modest amount of custom coding, irregular spatial embedding can be achieved within ABM
 - A guest lecture with an Alzheimer's application will give a glimpse as to how this can be achieved